



1 BACKGROUND OF THE INVENTION

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4 FIELD OF THE INVENTION

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6 The present invention relates generally to pressure

7 regulation and self-contained breathing systems such as those

8 used in scuba diving equipment and more specifically, to a new

9 improved means for automatically altering the breathing

10 characteristics of a demand-type regulator by automatic

11 adjustment of the venturi action in the regulator in accordance

12 with depth during diving.

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14

15 PRIOR ART

16

17 Pressure regulators such as those employed in underwater

18 breathing apparatus, utilize the pressure differential on

19 opposite sides of a flexible diaphragm to operate an air valve

20 which supplies air to a breathing chamber from which the diver

21 breathes. Typically, such a flexible diaphragm is mounted to

22 cover an opening in the wall of the breathing chamber whereby

23 expansion of the diaphragm actuates the air valve. More

24 specifically, when the diver inhales while the air inlet valve

25 is closed, the pressure in the breathing chamber is reduced

26 causing the diaphragm to bow inwards inside the breathing

27 chamber and thereby allowing an air inlet valve to open. When

28 the diver exhales, pressure in the chamber increases causing

29 the diaphragm to move out to its original condition thereby

30 closing the air inlet valve.

Recent prior art includes disclosure of various pressure regulator structures which provide a reduction in the effort required by the diver to breathe from such regulators. More specifically, regulators have been designed so that a portion of the inlet air travels into the breathing mouthpiece area in the form of a stream of air which produces a venturi effect. This venturi effect further reduces the pressures in the breathing chamber so that in effect the diver is not necessarily doing all the work required to sufficiently reduce the breathing chamber pressure to pull in and retain the diaphragm and cracking effort force setting whereby to open the air inlet valve. Thus, the venturi effect makes its easier for the diver to inhale air from the regulator. Breathing regulators which employ such venturi-type action to assist in responding to the breathing demand of the diver are highly advantageous. Unfortunately, they are not always optimally configured for the breathing requirements for each diver or for particular diving depths where ambient pressure increases as a function of depth thereby changing the parameters for the diver's degree of breathing difficulty and breathing requirements.

In most scuba diving situations, the requirement for the second stage regulator can change. On the surface, the regulator must be stable. The second stage should not accidentally flow air without stopping on its own. Unfortunately, when a scuba regulator is tuned for stable surface operation (no venturi), the performance under deeper diving conditions can suffer. And if the regulator second stage is adjusted for deep diving, the surface performance can be too sensitive causing uncontrolled free flow of air forcing the scuba diver to manually stop the flow of air by blocking

1 the mouthpiece exit with his finger or glove.

2
3 In response to this disadvantage of an otherwise advantageous
4 concept, prior art patents have addressed various ways of
5 altering venturi action in the regulator automatically during
6 the breathing cycle. Thus, for example Patent No. 4,214,580 to
7 Pedersen discloses a breathing apparatus of the venturi action
8 regulator-type hereinabove discussed which utilizes an
9 additional moving baffle to alter the venturi effect after the
10 diver initially inhales. While such modification to the
11 venturi action is accomplished automatically, it does not
12 appear to be responsive to ambient water pressure variation
13 with depth.

14
15 Another prior art patent which addresses manual control
16 aspect of venturi-type demand regulators is disclosed in Patent
17 No. 4,147,176 to Christianson. This patent discloses the
18 concept of using a conical platform in conjunction with a
19 diaphragm wherein the diaphragm gradually flattens down against
20 the platform to reduce the effect of sensing area during the
21 breathing cycle. One embodiment is disclosed which has an
22 adjustable aspirator which permits the diver to externally
23 change the aspiration effect during the dive. Unfortunately,
24 there is an inherent disadvantage in the manner in which the
25 diaphragm and conical platform interact to control the venturi
26 assist during the breathing cycle which makes the performance
27 of the regulator substantially non-uniform during the breathing
28 cycle. As a result, the diver may adjust the regulator
29 characteristics to provide him with an advantageous operation
30 for one aspect of the breathing cycle only to find that during
31 another portion of the breathing cycle the adjustment is
32 unsuitable.

1 U.S. Patent No. 3,526,241 to Veit is directed to an oxygen-
2 air diluter for breathing apparatus employing an altitude
3 controlled Venturi mixing mechanism. Referring to FIG. 1, the
4 diluter apparatus is shown in its low altitude configuration
5 with conically shaped valve member 24 sealing conical valve
6 seat 18. Referring to FIG. 2, the diluter is shown in a high
7 altitude configuration. Here, bellows 47 has expanded due to
8 the lower air pressure exposed through aperture 49. Through
9 the interaction of the associated elements, conically shaped
10 valve member 24 is drawn away from conical valve seat 18,
11 thereby permitting oxygen to enter Venturi throat portion 22
12 from inlet 12.

13
14 U.S. Patent No. 4,796,618 to Garraffa is directed to a
15 breathing regulator apparatus having a manually adjusted
16 Venturi valve. Referring to FIG. 2, flow vane 22 is adjusted
17 so that all or virtually all of the air stream 28 emanating
18 from the air inlet valve 18 is directed into the mouthpiece
19 tube 19. Referring to FIG. 3, the position of flow vane 22 has
20 the effect of splitting the air stream 28 into two components,
21 namely, a first component 30 which is directed towards the
22 diaphragm 16 and a second component 32 which is directed
23 through the mouthpiece tube 19.

24
25 U.S. Patent No. 3,308,817 to Seeler is directed to a
26 reduction regulator valve for a scuba system having an
27 automatic depth controlled mixing adjustment system. Referring
28 to the Drawings, when a diver descends into deeper water, the
29 pressure exerted by the water within the end cap 25 on the
30 bellows 49 will contract the bellows, which in turn will permit
31 the coil spring 57 to extend, thereby lessening the pressure on
32 the diaphragm 54, permitting the valve 36 to close under the

1 action of the valve spring 37. The reduction of the pressure
2 exerted on the diaphragm 54 and the closing of the valve 36
3 reduces the pressure exerted on the housing side of the
4 diaphragm 63, permitting the spring 61 to press against the
5 diaphragm 63 and urge the rod 64 against the valve 41, opening
6 the passageway 65 to the tank containing a mixture of helium
7 and oxygen to admit same to the outlet port 23 into the
8 mouthpiece 73. Note, however, that this reference does not
9 employ a Venturi action.

10
11 U.S. Patent No. 5,368,020 to Beux is directed to a depth
12 controlled automatic mixing system for breathing apparatus.
13 FIG. 7 shows a type B reducer which increases the flow of gas
14 with increasing environmental pressure. This reducer comprises
15 a body 200, a diaphragm 201 cooperating with a disk 202 which,
16 by means of a mechanical connection member 203, cooperates with
17 a further disk 204 associated with a diaphragm 205 which, by
18 means of the disk 206 and the mechanical connection element
19 207, cooperates with a plug 208. Stress is placed on the
20 diaphragm 201 by environmental pressure, that is to say, by
21 water pressure, which acts directly on the surface of the
22 diaphragm 201 through the bore 209, providing the calibration
23 thrust which varies according to environmental pressure.
24 Through the flow restriction nozzle 212, the gas enters the
25 tube 213 which sends it to the inspiration bag.

1 Many scuba manufacturers solve the surface free flow problem
2 by positioning a blade or vane near the air exit point of the
3 second stage. The result is that air that travels out of the
4 valve mechanism (located inside second stage) is blocked or re-
5 routed back inside the second stage case before its velocity
6 can create a venturi or free flow condition of the second
7 stage.

8
9 These blades or vanes can also be manually re-positioned to
10 allow rapid unobstructed air passage through the second stage
11 causing the second stage to venturi assist (free flow). This
12 venturi assist will increase the regulator performance by
13 lowering the mechanical effort (or diver inhalation effort)
14 required to breath the second stage.

15
16 A disadvantage of the manual design is that the scuba
17 regulator second stage is located in the mouth and held by the
18 teeth by means of a rubber mouthpiece. Locating the manual
19 switch is difficult and confusing. This adjustment is made by
20 feel not sight when the regulator is in the mouth. These
21 manual switches tend to be small and located in difficult
22 locations to reach with the fingers. Also, divers that wear a
23 thermally protecting glove cannot locate these manual switches.
24 Sometimes the adjustment is so difficult to locate, the entire
25 second stage must be removed from the mouth so the diver can
26 see where the exact tuning position is with respect to
27 incremental notching or indicator numbers. This is deemed an
28 unsafe procedure. A better non-manual flow control is needed.

1 There is, therefore, a need to provide a regulator which is
2 of the breathing demand-type, which utilizes venturi assist to
3 control the degree of air inlet opening, which provides the
4 user with an automatic adjustment for varying the venturi
5 effect during the dive and which, most importantly, provides
6 either a constant or a smooth changing level of performance
7 during the entire breathing cycle by adjustment for depth of
8 the diver during the dive.

SUMMARY OF THE INVENTION

The present invention comprises an inhalation demand breathing regulator which solves the aforementioned need. More specifically, the present invention comprises a breathing regulator in which an automatically adjustable flow deflector or flow vane is utilized to create a diversion of high velocity air to direct it at the mouthpiece area of the regulator housing whereby to provide an automatic means for increasing the vacuum assist in demand regulators. When the flow vane is withdrawn, the air stream is redirected back into the housing, thus balancing the low pressure area behind the diaphragm which prevents a free flow condition and allows the demand regulator to be less sensitive to ambient water conditions. The automatic flow control, or A.F.C., is used in scuba diving regulator second stages to automatically regulate the venturi or aspirated flow of air to the diver at different depths. A.F.C. allows the regulator second stage to be stable on the surface (no venturi) and yet provides excellent performance at depth (maximum venturi) automatically freeing the diver of making any needed manual adjustments to the second stage under water. Unlike the prior art, the present invention does not depend upon the relative position of a diaphragm and for example, a conical platform which relationship varies non-linearly during a breathing cycle. The effect of the present invention is a venturi assisted demand regulator which is less complex in structure, more reliable and more predictable in performance and which varies automatically with depth increasing the venturi effect or assist level as the diver descends and reducing the venturi effect or assist level as the diver ascends.

OBJECTS OF THE INVENTION

It is therefore a principal object of the present invention to provide an improved venturi assisted demand-type breathing regulator primarily for use in diving and which entirely overcomes or at least substantially reduces the deficiencies of the prior art.

It is an additional object of the present invention to provide a venturi assisted demand-type breathing regulator primarily for use by scuba divers wherein the extent to which the venturi action affects the air flow is automatically varied during the dive in accordance with the depth of the diver.

It is still an additional object of the present invention to provide a venturi assisted demand breathing regulator utilizing a deflector vane which, depending upon the position of the vane determined by ambient water pressure, increasingly deflects a portion of the air stream toward the mouthpiece thus increasing the venturi effect thereby allowing the demand regulator to be responsive to ambient water conditions.

It is still an additional object of the present invention to provide an automatically adjustable venturi assisted demand breathing regulator particularly advantageous for scuba diving wherein depth of the diver automatically adjusts a device for interfering with the air stream emanating from the inlet valve into the housing whereby the degree to which the venturi effect aids the diver's breathing may be automatically varied so that the breathing effort is compensated in accordance with the diver's depth.

BRIEF DESCRIPTION OF THE DRAWINGS

The aforementioned objects and advantages of the present invention as well as additional objects and advantages thereof will be more fully understood hereinafter as a result of a detailed description of a preferred embodiment of the invention when taken in conjunction with the following drawings in which:

FIG. 1 is a top cross-sectional view of the breathing regulator of the present invention configured for operation at the surface;

FIG. 2 is a similar top cross-sectional view of the invention illustrating the manner in which the invention automatically adjusts venturi effect for depth;

FIG. 3 is a side cross-sectional view of the breathing regulator illustrating air flow with automatic adjustment for surface operation; and

FIG. 4 is a similar side cross-sectional view of the breathing regulator illustrating air flow with automatic adjustment for operation at or near maximum depth.

DESCRIPTION OF A PREFERRED EMBODIMENT

Referring first to FIG. 1 it will be seen that the improved breathing regulator apparatus 10 of the present invention comprises a demand valve 12 having an air inlet tube 13 which will be connected to a suitable source of pressurized air supply in a well-known manner. Apparatus 10 also comprises a diaphragm 16 cooperating with a lever 20 to selectively actuate the air inlet demand valve 12 in response to the breather's inhalation requirements. Lever 20 unseats a poppet 22 from an orifice 14 to open valve 12. Apparatus 10 also provides a mouthpiece tube 28 connected to a mouthpiece (not shown) which is normally retained within the mouth of the user permitting access to incoming air from air passage 26. Apparatus 10 also provides a piston-controlled deflector or flow vane 30 which comprises the critical component of the present invention as is hereinafter discussed. Apparatus 10 also comprises exhaust ports and an exhaust valve (not shown) which in combination, provide means for exhausting the exhalation gas of the user through the regulator 10.

The position of diaphragm 16 is determined by the relative pressure differential on opposing sides of the diaphragm within the diaphragm cover 18 and housing 19. The center of the diaphragm is provided with a bearing surface which bears against the lever 20 the position of which determines whether the air inlet valve 12 is opened or closed.

1 When the user begins to inhale through the mouthpiece tube
2 28, the air pressure in the interior of the regulator is
3 reduced. This reduction in the air pressure causes the central
4 portion of diaphragm 16 to be sucked in towards the mouthpiece
5 tube and compresses lever 20 and opens the air inlet valve 12.
6 When the air inlet valve is opened, a stream of air is
7 generated and flows through air exit 24 in the general
8 direction of the mouthpiece tube 28 through the mouthpiece tube
9 passage 26 thereby responding to the user's inhalation
10 requirements, but also creating a venturi effect generated by
11 the high velocity air emanating from the air inlet valve 12.
12 This high velocity air pulls the still air inside the regulator
13 along with it, causing a secondary pressure drop or a vacuum to
14 exist inside the interior of the regulator.

15
16 The initial inhalation effort required to open the air inlet
17 valve 12 is commonly referred to as the cracking effort. The
18 extent of inhalation effort required after the cracking effort
19 level has been reached depends on the extent to which the level
20 of venturi assist is utilized during the remainder of the
21 breathing cycle. In those prior art regulator devices in which
22 virtually no further breathing effort is required, the user may
23 incur a disadvantageous condition in which the air inlet valve
24 remains open due to the venturi effect thus creating a
25 condition of free flow which in effect forces air into the
26 user's lungs. Such a condition may be desirable for the
27 experienced diver under certain deep dive or other difficult
28 breathing conditions. However, the less experienced diver may
29 find such a free flow condition to be frightening or otherwise
30 disadvantageous. For example, such free flow conditions
31 occurring when the regulator is out of the mouth of the user
32 can create a panicky environment for the diver who feels great

1 concern over the loss of air from his tanks.

2
3 In any case, as previously noted, the relevant prior art has
4 already disclosed means for manually changing the venturi
5 assist effect whereby to overcome the noted disadvantages of
6 those regulators which have employed full venturi assist
7 configurations. The present invention however provides a novel
8 means for automatically varying the venturi assist as a
9 function of depth. More specifically, FIGs. 1 and 2 illustrate
10 two different automatic adjustment configurations of the flow
11 deflector tip or vane 30 of the present invention.

12
13
14 AUTOMATIC FLOW CONTROL AT SURFACE OPERATION
15 (SEE FIGs. 1 and 3)

16
17 Air from the first stage is passed through an air pressure
18 hose to the orifice 14. As the diver demands air, the
19 inhalation diaphragm 16 bows inward and forces the demand lever
20 20 down moving the poppet 22 away from the orifice 14. Air
21 travels past the poppet and exits from the air exit 24 and into
22 the mouthpiece tube 28. Due to the position of the air exit,
23 the exiting air cannot build up enough velocity to sustain a
24 free flow venturi effect. The position of the deflector tip 30
25 is retracted in its surface resting position. A piston
26 comprising piston head 33 and piston rod 32 remains static by a
27 low ambient pressure in a pressure cavity 38 which merely
28 balances the pressure in a sealed pressure chamber 36. Spring
29 34 assures retraction of the flow vane and the surface
30 performance is stable due to no venturi, free flow.

1 As shown in FIG. 3, when the deflector tip 30 is in the
2 retracted position at or near the surface or zero depth, the
3 air stream bypasses the deflector tip. A significant portion
4 of the air flow from air exit 24 is redirected toward the
5 diaphragm after deflecting off of the top portion of the
6 mouthpiece tube 28.

7
8
9 AUTOMATIC FLOW CONTROL AT DEPTH OPERATION

10 (SEE FIGS. 2 and 4)

11
12 As the diver descends under water, ambient water pressure
13 increases in the ambient water pressure cavity 38 and presses
14 the piston head 33 and rod 32 forward, compressing the return
15 spring 34 and increasing the pressure in the sealed pressure
16 chamber 36. The deflector tip 30 now straightens the air
17 leaving the air exit 24 thus creating a venturi effect and
18 increasing regulator performance. As shown in FIG. 4, at
19 significant depths, the deflector tip 30 enters the air stream
20 deflecting a major portion toward the mouthpiece tube 28 and
21 through the passage 26. This deflected flow creates a vacuum
22 assist to bow the diaphragm 16 inwardly and lower the effort
23 required to sustain flow. As the diver ascends back to the
24 surface, the pressure is relieved from the ambient water
25 pressure cavity 38 and the deflector tip 30 returns to its
26 surface resting position and the second stage becomes stable
27 once again. The O-rings 40 and 41 assure pressure integrity of
28 chamber 36 and cavity 38 and retaining cap 42 secures return
29 spring 34 and the piston.

1 Thus it will be understood that the present invention
2 provides a novel second stage scuba diving breathing regulator
3 having automatic flow control wherein a venturi assist effect
4 is automatically adjusted with depth to provide no venturi
5 effect at the surface and an increasing venturi effect as the
6 diver descends.

7
8 Those having skill in the art to which the present invention
9 pertains, will now, as a result of the disclosure herein,
10 perceive various modifications which may be made to the
11 invention. By way of example, the precise location and
12 structure of the flow control mechanism may be altered while
13 still achieving the novel objective of automatic flow control
14 with depth of the diver as the variable parameter.
15 Furthermore, the deflector tip of the invention may be
16 configured to travel in either direction with increasing depth
17 and thus alter air flow either proportional to depth or
18 inversely proportional to depth. The latter configuration can
19 be used to increase vacuum assist with increasing depth by
20 altering the direction of the nominal air flow to provide more
21 deflection away from the mouthpiece tube with increasing
22 extension of the deflector tip at shallower depths. This would
23 constitute a reversal of the disclosed embodiment while
24 achieving the same result. Accordingly, all such modifications
25 are deemed to be within the scope of the invention which is to
26 be limited only by the appended claims and their equivalents.

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28 I
We claim:
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